# Constructive Polynomial Approximation on the Sphere 

Ian H. Sloan and Robert S. Womersley<br>School of Mathematics, University of New South Wales, Sydney 2052, Australia<br>E-mail: I.Sloan@unsw.edu.au, R.Womersley@unsw.edu.au

Communicated by Doron S. Lubinsky
Received December 8, 1998; accepted in revised form September 16, 1999


#### Abstract

This paper considers the problem of constructive approximation of a continuous function on the unit sphere $S^{r-1} \subseteq \mathbb{R}^{r}$ by a spherical polynomial from the space $\mathbb{P}_{n}$ of all spherical polynomials of degree $\leqslant n$. In particular, for $r=3$ it is shown that the hyperinterpolation approximation $L_{n} f$ (in which the Fourier coefficients in the exact $L_{2}$ orthogonal projection $P_{n} f$ are approximated by a positive weight quadrature rule that integrates exactly all polynomials of degree $\leqslant 2 n$ ) has the exact order $\left\|L_{n}\right\| \asymp n^{1 / 2}$ for its uniform norm, provided the underlying quadrature rule satisfies an additional "quadrature regularity" assumption. For $r=3$, this rate of growth is the same as that of $\left\|P_{n}\right\|$, and is known to be optimal among all linear projections on $\mathbb{P}_{n}$. For $r \geqslant 3$ an upper bound on $\left\|L_{n}\right\|$ of non-optimal asymptotic order $O\left(n^{(r-1) / 2}\right)$ also holds, without any special assumption on the quadrature rule. © 2000 Academic Press


## 1. INTRODUCTION

In this paper we consider polynomial approximations on the unit sphere $S^{r-1} \subseteq \mathbb{R}^{r}$ from the space of all spherical polynomials of degree at most $n$ (i.e. the space of all polynomials in $r$ variables restricted to $S^{r-1}$ ).

In particular, we shall show for $r=3$ that the hyperinterpolation approximation introduced in [17] can have the optimal order of growth for its operator norm among all linear projections considered as maps from $C\left(S^{r-1}\right)$ to $C\left(S^{r-1}\right)$, namely $O\left(n^{1 / 2}\right)$. The hyperinterpolation approximation $L_{n} f$ may be described as an approximation obtained from the partial sum of the Laplace (or Fourier) series for $f$, when the exact integrals in the $L_{2}$ inner products are approximated by a suitable quadrature rule: specifically, the quadrature rule must have positive weights, and must give the exact integral when applied to any polynomial of degree less than or equal to $2 n$. A formal description of the hyperinterpolation approximation is given in Section 3. Examples of suitable quadrature rules are considered in Section 6. The operator norm $\left\|L_{n}\right\|_{C \rightarrow C}$ of $L_{n}$ as a map from $C\left(S^{r-1}\right)$ to $C\left(S^{r-1}\right)$ is studied in Section 5, and for $r=3$ shown there to be bounded
by $n+1$ without further assumptions, and by $c n^{1 / 2}$ under a mild additional assumption on the quadrature rule.

The most studied polynomial approximation that needs only a finite number of point values of $f$ is the polynomial interpolant $\Lambda_{n} f$. This coincides with a given continuous function $f$ at a prescribed set of points $\left\{x_{1}, \ldots, x_{d_{n}}\right\} \subseteq S^{r-1}$, where $d_{n} \equiv d_{n}^{(r)}$ is the dimension of the space of spherical polynomials of degree at most $n$. Through the work of Reimer [16] and others, much is known about the norm $\left\|\Lambda_{n}\right\|_{C \rightarrow C}$ of $\Lambda_{n}$ as a map from $C\left(S^{r-1}\right)$ to $C\left(S^{r-1}\right)$, yet the problem of finding a set of interpolation points that yields a good uniform approximation, or of understanding how good such approximations can be, remains elusive. A bound on $\left\|\Lambda_{n}\right\|_{C \rightarrow C}$ given by Reimer [16] has, for $r=3$, the form $(n+1)\left(\lambda_{\text {avg }} / \lambda_{\text {min }}\right)^{1 / 2}($ see Section 7), where $\lambda_{\text {avg }}$ and $\lambda_{\text {min }}$ are the average and minimum eigenvalues of a certain positive-definite matrix. The ratio $\lambda_{\text {avg }} / \lambda_{\text {min }}$ depends on the choice of points $\left\{x_{1}, \ldots, x_{d_{n}}\right\}$, but beyond the fact that $\lambda_{\text {avg }} / \lambda_{\min } \geqslant 1$ and the less obvious fact (shown by Reimer [16]) that $\lambda_{\text {avg }} / \lambda_{\min }>1$ for $r \geqslant 3$ and $n \geqslant 3$, little seems to be known about its possible dependence on $r$ and $n$. One known result (see Section 7) is that for $r=3$ there exist interpolation points $\left\{x_{1}, \ldots, x_{d_{n}}\right\}$ (namely the "extremal fundamental systems" of Reimer [16]) such that $\left\|\Lambda_{n}\right\|_{C \rightarrow C} \leqslant(n+1)^{2}$. However, this result is almost certainly very pessimistic.

The simpler problem of the approximation properties of the hyperinterpolation operator $L_{n}$ as a map from $C\left(S^{r-1}\right)$ to $L_{2}\left(S^{r-1}\right)$ was studied in [17]. In that setting the approximation properties of $L_{n}$ are in a certain sense ideal, in that the norm of $L_{n}$ is shown in [17] to be given by

$$
\begin{equation*}
\left\|L_{n}\right\|_{C \rightarrow L_{2}}=\left|S^{r-1}\right|^{1 / 2} \tag{1.1}
\end{equation*}
$$

where $\left|S^{r-1}\right|$ denotes the surface area of the unit sphere. This is the best possible result, as is easily seen by considering the operator applied to the constant function 1. In contrast, it has been shown in [18] that for $r \geqslant 3$ and $n \geqslant 3$ the interpolation operator $\Lambda_{n}$ necessarily has a larger norm in the $C$ to $L_{2}$ sense, that is

$$
\begin{equation*}
\left\|\Lambda_{n}\right\|_{C \rightarrow L_{2}}>\left|S^{r-1}\right|^{1 / 2} \quad \text { if } r \geqslant 3 \text { and } n \geqslant 3 \tag{1.2}
\end{equation*}
$$

The proof of the latter result in [18] is by contradiction, and therefore gives no insight into the extent to which the inequality in (1.2) departs from equality.

The present paper, concentrating on the $C\left(S^{r-1}\right)$ to $C\left(S^{r-1}\right)$ setting, extends the known theoretical results for hyperinterpolation.

The results of computational experiments for the two approximation schemes will be published elsewhere.

Generic constants are denoted by $c$, while more specific constants are denoted $c_{1}, c_{2}, a_{1}, a_{2}$, etc.

## 2. PRELIMINARIES

For given $n \geqslant 0$, let $\mathbb{P}_{n} \equiv \mathbb{P}_{n}^{(r)}$ be the set of spherical polynomials of degree $\leqslant n$ in $r$ variables; i.e. the set of all polynomials in $r$ variables of degree at most $n$ restricted to $S^{r-1}$, the unit sphere in $\mathbb{R}^{r}$.

A popular basis for $\mathbb{P}_{n}^{(r)}$ is the set of spherical harmonics [14]

$$
\left\{Y_{\ell, k}^{(r)}: 1 \leqslant k \leqslant N(r, \ell), 0 \leqslant \ell \leqslant n\right\},
$$

where

$$
N(r, 0)=1, \quad N(r, \ell)=\frac{2 \ell+r-2}{\ell}\binom{\ell+r-3}{\ell-1} \quad \text { for } \quad \ell \geqslant 1 .
$$

We shall assume that the spherical harmonics are normalized so that

$$
\int_{S^{r-1}} Y_{\ell, k}^{(r)}(x) Y_{\ell^{\prime}, k^{\prime}}^{(r)}(x) d x=\delta_{\ell \ell^{\prime}} \delta_{k k^{\prime}}
$$

where $d x$ denotes surface measure on $S^{r-1}$. The dimension of the space $\mathbb{P}_{n}^{(r)}$ we denote by

$$
\begin{equation*}
d_{n} \equiv d_{n}^{(r)}=\sum_{\ell=0}^{n} N(r, \ell)=N(r+1, n) . \tag{2.1}
\end{equation*}
$$

For example, in the important special case $r=3$ we have $N(3, \ell)=2 \ell+1$ and $d_{n}=(n+1)^{2}$.

The addition theorem of spherical harmonics [14] will play an important role. It states

$$
\begin{equation*}
\sum_{k=1}^{N(r, \ell)} Y_{\ell, k}^{(r)}(x) Y_{\ell, k}^{(r)}(y)=\frac{N(r, \ell)}{\left|S^{r-1}\right|} P_{\ell}^{(r)}(x \cdot y), \tag{2.2}
\end{equation*}
$$

where $x \cdot y$ is the inner product in $\mathbb{R}^{r},\left|S^{r-1}\right|$ is the surface area of the unit sphere,

$$
\left|S^{r-1}\right|=\frac{r \pi^{r / 2}}{\Gamma(1+r / 2)},
$$

and $P_{\ell}^{(r)}$ is the Legendre polynomial of degree $\ell$ in $r$ dimensions, normalized by $P_{\ell}^{(r)}(1)=1$.

## 3. THE APPROXIMATIONS DEFINED

For given dimension $r$ and degree $n$, let $X \equiv X_{n}^{(r)}=\left\{x_{1}, \ldots, x_{d_{n}}\right\} \subseteq S^{r-1}$ be a "fundamental system" of points on the sphere, meaning that the only member of $\mathbb{P}_{n}^{(r)}$ that vanishes at every point $x_{j}, j=1, \ldots, d_{n}$, is the zero polynomial.

Given an arbitrary $f \in C\left(S^{r-1}\right)$, we denote by $\Lambda_{n} f$ the unique polynomial in $\mathbb{P}_{n}$ that interpolates $f$ at each point of the fundamental system, that is

$$
\begin{equation*}
\Lambda_{n} f \in \mathbb{P}_{n}^{(r)}, \quad \Lambda_{n} f\left(x_{j}\right)=f\left(x_{j}\right), \quad j=1, \ldots, d_{n} \tag{3.1}
\end{equation*}
$$

As a prelude to the introduction of the hyperinterpolation approximation, it is convenient to introduce an intermediate approximation, which is theoretically simpler but harder to compute, namely the $L_{2}$ orthogonal projection of $f$ onto $\mathbb{P}_{n}^{(r)}$, given by

$$
\begin{equation*}
P_{n} f=\sum_{\ell=0}^{n} \sum_{k=1}^{N(r, \ell)}\left(f, Y_{\ell, k}^{(r)}\right) Y_{\ell, k}^{(r)}, \tag{3.2}
\end{equation*}
$$

where ( $\cdot, \cdot$ ) is the $L_{2}$ inner product on $S^{r-1}$,

$$
(u, v):=\int_{S^{r-1}} u(x) v(x) d x
$$

The hyperinterpolation approximation $L_{n} f$ is obtained by approximating the inner product in the Definition (3.2) of $P_{n} f$ by a positive-weight quadrature rule with the property of integrating all spherical polynomials of degree $\leqslant 2 n$ exactly. Thus the hyperinterpolation approximation has the form

$$
\begin{equation*}
L_{n} f=\sum_{\ell=0}^{n} \sum_{k=1}^{N(r, \ell)}\left(f, Y_{\ell, k}^{(r)}\right)_{m} Y_{\ell, k}^{(r)}, \tag{3.3}
\end{equation*}
$$

where $(\cdot, \cdot)_{m}$ is a discrete version of the inner product obtained by application of an $m$-point quadrature formula,

$$
(u, v)_{m}:=\sum_{j=1}^{m} w_{j} u\left(t_{j}\right) v\left(t_{j}\right),
$$

and where the weights $w_{j}$ and points $t_{j}$ in the quadrature rule $Q$,

$$
\begin{equation*}
Q g:=\sum_{j=1}^{m} w_{j} g\left(t_{j}\right) \approx \int_{S^{r-1}} g(x) d x, \tag{3.4}
\end{equation*}
$$

must satisfy

$$
\begin{equation*}
w_{j}>0, \quad t_{j} \in S^{r-1}, \quad j=1, \ldots, m, \tag{3.5}
\end{equation*}
$$

and

$$
\begin{equation*}
Q p=\int_{S^{r-1}} p(x) d x, \quad \forall p \in \mathbb{P}_{2 n}^{(r)} \tag{3.6}
\end{equation*}
$$

According to [17], it follows from the definition that $m \geqslant d_{n}$.
Note that the hyperinterpolation approximation $L_{n} f$ depends on the choice of quadrature rule $Q$, just as the interpolation approximation $\Lambda_{n} f$ depends in the choice of fundamental system $X$. The notation will usually not make this dependence explicit.

All three of the approximations described here are linear projections onto $\mathbb{P}_{n}^{(r)}$, in that

$$
p \in \mathbb{P}_{n}^{(r)} \Rightarrow \Lambda_{n} p=P_{n} p=L_{n} p=p .
$$

In the last case this follows by observing for $p \in \mathbb{P}_{n}^{(r)}$ that

$$
L_{n} p=\sum_{\ell=0}^{n} \sum_{k=1}^{N(r, \ell)}\left(p, Y_{\ell, k}^{(r)}\right)_{m} Y_{\ell, k}^{(r)}=\sum_{\ell=0}^{n} \sum_{k=1}^{N(r, \ell)}\left(p, Y_{\ell, k}^{(r)}\right) Y_{\ell, k}^{(r)}=p,
$$

where the second equality follows from the exactness of the quadrature rule for polynomials of degree $\leqslant 2 n$, and the last from the fact that the sum is just the Laplace or Fourier series for the polynomial $p$.

## 4. CONSTRUCTING $\Lambda_{n} f$ AND $L_{n} f$

In this section we consider alternative formulas for constructing $\Lambda_{n} f$ and $L_{n} f$, given a fundamental system $X$ in the first case, and a quadrature rule $Q$ in the second. At the same time we shall be developing reproducingkernel representations that will be needed in the later theoretical analysis.

The most obvious way to compute the interpolant $\Lambda_{n} f$ is to represent it as a linear combination of spherical harmonics,

$$
\begin{equation*}
\Lambda_{n} f=\sum_{\ell=0}^{n} \sum_{k=1}^{N(r, \ell)} a_{\ell, k} Y_{\ell, k}^{(r)}, \tag{4.1}
\end{equation*}
$$

where the coefficients $a_{\ell, k}$ must satisfy, from the interpolating Property 3.1, the linear system

$$
\begin{equation*}
\sum_{\ell=0}^{n} \sum_{k=1}^{N(r, \ell)} Y_{\ell, k}^{(r)}\left(x_{j}\right) a_{\ell, k}=f\left(x_{j}\right), \quad j=1, \ldots, d_{n} \tag{4.2}
\end{equation*}
$$

The matrix $\left\{Y_{\ell, k}^{(r)}\left(x_{j}\right)\right\}$ in this linear system is not singular, because of the assumption that $X=\left\{x_{1}, \ldots, x_{d_{n}}\right\}$ is a fundamental system. While the matrix elements $Y_{t, k}^{(r)}\left(x_{j}\right)$ with fixed $x_{j}$ can be computed relatively efficiently by exploiting recurrence relations of the spherical harmonics, the time for computing $\Lambda_{n} f$ will often be dominated by the time needed to solve the dense linear system (4.2). In contrast, the hyperinterpolation approximation $L_{n} f$ is already represented as a linear combination of spherical harmonics by the Definition (3.3), and does not need the solution of a linear system.

We develop here alternative representations of $\Lambda_{n} f$ and $L_{n} f$ (see (4.10) and (4.13) below), which may sometimes be preferred in practice because of their simplicity; in particular, explicit computation of spherical harmonics is avoided in these formulas.

To this end, it is useful to introduce the kernel $G_{n}(\cdot, \cdot)=G_{n}^{(r)}(\cdot, \cdot)$, defined by

$$
\begin{equation*}
G_{n}(x, y):=\sum_{\ell=0}^{n} \sum_{k=1}^{N(r, t)} Y_{\ell, k}^{(r)}(x) Y_{\ell, k}^{(r)}(y), \quad x, y \in S^{r-1} \tag{4.3}
\end{equation*}
$$

This is a "reproducing kernel" in $\mathbb{P}_{n}^{(r)}$, because of the following elementary but important property:

## Lemma 4.1 (Reimer [16])

$$
\left(p, G_{n}(\cdot, x)\right)=p(x) \quad \forall p \in \mathbb{P}_{n}^{(r)} .
$$

Proof. For $p \in \mathbb{P}_{n}^{(r)}$, the Definition 4.3 gives

$$
\left(p, G_{n}(\cdot, x)\right)=\sum_{\ell=0}^{n} \sum_{k=1}^{N(r, \ell)}\left(p, Y_{\ell, k}^{(r)}\right) Y_{\ell, k}^{(r)}(x),
$$

which is simply the Laplace series representation of the spherical polynomial $p(x)$.

It will be important to us that $G_{n}(x, y)$ is easily computed. The principal simplification is that $G_{n}(x, y)$ is "bizonal;" that is, its value depends only on the inner product $x \cdot y$ of the unit vectors $x$ and $y$. This follows from the addition theorem for spherical harmonics (2.2), which yields

$$
\begin{equation*}
G_{n}(x, y)=\widetilde{G}_{n}(x \cdot y), \quad x, y \in S^{r-1}, \tag{4.4}
\end{equation*}
$$

where

$$
\begin{equation*}
\tilde{G}_{n}(z)=\frac{1}{\left|S^{r-1}\right|} \sum_{\ell=0}^{n} N(r, \ell) P_{\ell}^{(r)}(z), \quad z \in[-1,1] . \tag{4.5}
\end{equation*}
$$

For example, if $r=3$ we have

$$
\begin{equation*}
\tilde{G}_{n}(z)=\frac{1}{4 \pi} \sum_{\ell=0}^{n}(2 \ell+1) P_{\ell}(z), \tag{4.6}
\end{equation*}
$$

where $P_{\ell}(\cdot)$ is the usual Legendre polynomial. This $r=3$ result can be written in closed form, as pointed out by [10], in terms of the Jacobi polynomial $P_{n}^{(1,0)}$ (in the notation of Szegö [20]) appropriate to the weight function ( $1-z$ ). The closed form $r=3$ result (using [20, Equation (4.5.3)]) is

$$
\begin{equation*}
\tilde{G}_{n}(z)=\frac{n+1}{4 \pi} P_{n}^{(1,0)}(z) . \tag{4.7}
\end{equation*}
$$

Of particular interest to us will be the value of $\tilde{G}_{n}(1)$, i.e. the value of $G_{n}(x, y)$ when $y=x$. According to (4.5) and (2.1) it is given by, as pointed out by Reimer [16],

$$
\begin{equation*}
\widetilde{G}_{n}(1)=\frac{d_{n}}{\left|S^{r-1}\right|} . \tag{4.8}
\end{equation*}
$$

For example, for $r=3$ it has the value

$$
\tilde{G}_{n}(1)=\frac{(n+1)^{2}}{4 \pi} .
$$

To each point $x_{j}$ of the fundamental system $X=\left\{x_{1}, \ldots, x_{d_{n}}\right\}$ we may define a "kernel polynomial" $g_{j} \in \mathbb{P}_{n}^{(r)}$, by

$$
\begin{equation*}
g_{j}(x):=G_{n}\left(x, x_{j}\right)=\widetilde{G}_{n}\left(x \cdot x_{j}\right), \quad j=1, \ldots, d_{n} . \tag{4.9}
\end{equation*}
$$

We shall say that $g_{j}$ is the kernel polynomial with axis $x_{j}$. It is easy to see that the set $\left\{g_{1}, \ldots, g_{d_{n}}\right\} \subseteq \mathbb{P}_{n}^{(r)}$ is linearly independent, because of the assumption that $X$ is a fundamental system, thus this set spans $\mathbb{P}_{n}^{(r)}$. Therefore the interpolating polynomial $\Lambda_{n} f$ may now, if we wish, be expressed in the form

$$
\begin{equation*}
\Lambda_{n} f=\sum_{j=1}^{d_{n}} e_{j} g_{j}, \tag{4.1.1}
\end{equation*}
$$

where the real coefficients $e_{j}$ are determined by the linear system

$$
\begin{equation*}
\sum_{j=1}^{d} G_{i j} e_{j}=f\left(x_{i}\right), \quad i=1, \ldots, d_{n} \tag{4.11}
\end{equation*}
$$

with

$$
\begin{equation*}
G_{i j}:=g_{j}\left(x_{i}\right)=\widetilde{G}_{n}\left(x_{i} \cdot x_{j}\right)=G_{n}\left(x_{i}, x_{j}\right), \quad i, j=1, \ldots, d_{n} . \tag{4.12}
\end{equation*}
$$

The computation of the interpolant $\Lambda_{n} f$ via (4.10), (4.11), and (4.12), is easy to implement, requiring only the repeated evaluation of the polynomial $\widetilde{G}_{n}$ and the solution of a linear system for $r=3$. The time for computing the matrix $\left(G_{i j}\right)$ is of order $O\left(n d_{n}^{2}\right)=O\left(n^{5}\right)$, and the time for a single evaluation of $\Lambda_{n} f(x)$ is of order $O\left(n d_{n}\right)=O\left(n^{3}\right)$, which in practice will be unimportant compared with the $O\left(d_{n}^{3}\right)=O\left(n^{6}\right)$ time needed to solve the linear system, unless the interpolant is required at very many points.

Now we describe an analogous expression for the hyperinterpolation approximation $L_{n} f$, obtained by interchanging the order of summation in (3.3). In this way we obtain

$$
\begin{equation*}
L_{n} f=\sum_{j=1}^{m} w_{j} f\left(t_{j}\right) g_{j}, \tag{4.13}
\end{equation*}
$$

where this time $g_{j}$ denotes the kernel polynomial with axis $t_{j}$, that is

$$
\begin{equation*}
g_{j}(x):=G_{n}\left(x, t_{j}\right)=\widetilde{G}_{n}\left(x \cdot t_{j}\right), \quad j=1, \ldots, m . \tag{4.14}
\end{equation*}
$$

(It will be clear from the context whether $g_{j}$ has as its axis the point $x_{j}$ of the fundamental system $X$, or the point $t_{j}$ of the quadrature rule $Q$.)

We observe that (4.13) has a particularly simple structure, similar to the formula (4.10) for $\Lambda_{n} f$, but requiring no solution of a linear system.

## 5. HYPERINTERPOLATION IN THE UNIFORM NORM

In this section we study the hyperinterpolation operator $L_{n}$ as a map from $C\left(S^{r-1}\right)$ to $C\left(S^{r-1}\right)$.

Because $L_{n}$ is a linear projection on $\mathbb{P}_{n}$ we are able to argue in a standard way, that

$$
\left\|L_{n} f-f\right\|_{\infty}=\left\|L_{n}(f-\chi)-(f-\chi)\right\|_{\infty}
$$

for $\chi$ an arbitrary polynomial in $\mathbb{P}_{n}$. From this it follows immediately that

$$
\begin{equation*}
\left\|L_{n} f-f\right\|_{\infty} \leqslant\left(1+\left\|L_{n}\right\|_{C \rightarrow C}\right) E_{n}(f), \tag{5.1}
\end{equation*}
$$

where

$$
\left\|L_{n}\right\|_{C \rightarrow C}=\sup _{f \in C, f \neq 0} \frac{\left\|L_{n} f\right\|_{\infty}}{\|f\|_{\infty}},
$$

and $E_{n}(f)$ is the error of best uniform approximation,

$$
E_{n}(f)=\inf _{\chi \in \mathbb{P}_{n}}\|f-\chi\|_{\infty} .
$$

Thus our task reduces, in the usual way, to the study of the norm of the operator $L_{n}$ in the setting $C$ to $C$.
To guide us in assessing the quality of $L_{n}$, it is useful to recall first that $P_{n}$, the $L_{2}$ orthogonal projection, is the minimal norm projection in the setting $C$ to $C$ : that is, if $\Omega$ is an arbitrary linear projection onto $\mathbb{P}_{n}^{(r)}$, then

$$
\left\|P_{n}\right\|_{C \rightarrow C} \leqslant\|\Omega\|_{C \rightarrow C} .
$$

This result was proved by Berman [2] for the case $r=2$, and extended to general $r$ by Daugavet [5]; a proof for $r \geqslant 3$ is given by Reimer [16]. Moreover, for $r=2$ it is known (see [6]) that

$$
\left\|P_{n}\right\|_{C \rightarrow C} \asymp \log n
$$

while for $r=3$ it was shown by [11] that

$$
\begin{equation*}
\left\|P_{n}\right\|_{C \rightarrow C} \asymp n^{1 / 2} \tag{5.2}
\end{equation*}
$$

where $a_{n} \asymp b_{n}$ means that there exist positive constants $c_{1}$ and $c_{2}$ such that $c_{1} a_{n} \leqslant b_{n} \leqslant c_{2} a_{n}$. The generalization of this result to arbitrary $r \geqslant 3$, discussed by Reimer [16, Section 11], is

$$
\begin{equation*}
\left\|P_{n}\right\|_{C \rightarrow C} \asymp n^{(r-2) / 2} . \tag{5.3}
\end{equation*}
$$

There are two main results in this section. First, in Theorem 5.5 .2 we establish a general result, that $\left\|L_{n}\right\|_{C \rightarrow C}$ is bounded above by $d_{n}^{1 / 2}$. For the important special case $r=3$ Theorem 5.5.2 yields

$$
\left\|L_{n}\right\|_{C \rightarrow C} \leqslant n+1 .
$$

This is an improvement on the result $\left\|L_{n}\right\|_{C \rightarrow C} \leqslant c n^{2}$ obtained by [10, Theorem 3.2(i) ]. On the other hand, for all $r \geqslant 3$ the rate of growth of $d_{n}^{1 / 2}$ with $n$, namely $O\left(n^{(r-1) / 2}\right)$, is worse by a factor of $n^{1 / 2}$ than the optimal result for $\left\|P_{n}\right\|_{C \rightarrow C}$ given by (5.3). That prompts the question of whether better results for $\left\|L_{n}\right\|_{C \rightarrow C}$ can be achieved.
In Theorem 5.5.4 we obtain, for the special case $r=3$ and under a mild additional assumption on the quadrature rule, the improved result that $\left\|L_{n}\right\|_{C \rightarrow C} \asymp n^{1 / 2}$, which, as we have noted, is optimal with respect to order.

The following simple lemma provides the foundation for these results. In this lemma $g_{j}(x)=G\left(x, t_{j}\right)$ is the kernel polynomial with axis $t_{j}$, as in (4.14).

Lemma 5.5.1. The norm of the hyperinterpolation operator $L_{n}$ in the setting $C$ to $C$ is given by

$$
\left\|L_{n}\right\|_{C \rightarrow C}=\max _{x \in S^{r-1}} \sum_{j=1}^{m} w_{j}\left|g_{j}(x)\right| .
$$

Proof. From the expression (4.13) for $L_{n} f$ we have

$$
\left|L_{n} f(x)\right| \leqslant \sum_{j=1}^{m} w_{j}\left|f\left(t_{j}\right)\right|\left|g_{j}(x)\right| \leqslant \sum_{j=1}^{m} w_{j}\left|g_{j}(x)\right|\|f\|_{\infty},
$$

from which it follows that

$$
\begin{equation*}
\left\|L_{n} f\right\|_{\infty} \leqslant \max _{x \in S^{r-1}} \sum_{j=1}^{m} w_{j}\left|g_{j}(x)\right|\|f\|_{\infty}, \tag{5.4}
\end{equation*}
$$

where we exploit here the continuity of the spherical polynomials $g_{j}$ for $j=1$, ..., $m$.

The proof is completed by showing that there exists $f^{*} \in C\left(S^{r-1}\right)$, with $f^{*} \neq 0$, for which (5.4) is an equality. To this end, let $x_{0} \in S^{r-1}$ achieve the maximum in the sum in (5.4), i.e.

$$
\begin{equation*}
\sum_{j=1}^{m} w_{j}\left|g_{j}\left(x_{0}\right)\right|=\max _{x \in S^{r-1}} \sum_{j=1}^{m} w_{j}\left|g_{j}(x)\right| . \tag{5.5}
\end{equation*}
$$

Then define $f^{*} \in C\left(S^{r-1}\right)$ such that $\left\|f^{*}\right\|_{\infty}=1$ and

$$
f^{*}\left(t_{j}\right)=\operatorname{sign} g_{j}\left(x_{0}\right), \quad j=1, \ldots, m ;
$$

concrete constructions of $f^{*}$ satisfying these conditions can be accomplished in well-known ways. By (4.13) we now have

$$
L_{n} f^{*}(x)=\sum_{j=1}^{m} w_{j} f^{*}\left(t_{j}\right) g_{j}(x)=\sum_{j=1}^{m} w_{j} g_{j}(x) \operatorname{sign} g_{j}\left(x_{0}\right),
$$

and hence, on setting $x=x_{0}$,

$$
L_{n} f^{*}\left(x_{0}\right)=\sum_{j=1}^{m} w_{j}\left|g_{j}\left(x_{0}\right)\right|=\max _{x \in S^{r-1}} \sum_{j=1}^{m} w_{j}\left|g_{j}(x)\right|=\left\|L_{n} f^{*}\right\|_{\infty}
$$

so that (5.4) is an equality for $f=f^{*}$. This completes the proof.

With the aid of Lemma 5.5 .1 we can now turn to estimating the rate of growth of $\left\|L_{n}\right\|_{C \rightarrow C}$ with $n$. The first result needs no further assumptions.

Theorem 5.5.2. The norm of the hyperinterpolation operator in the setting $C$ to $C$ is bounded by

$$
\left\|L_{n}\right\|_{C \rightarrow C} \leqslant d_{n}^{1 / 2} .
$$

Proof. Let $x_{0} \in S^{r-1}$ satisfy (5.5), as in the proof of Lemma 5.5.1. Then that lemma gives, by the use of (4.14) and the Cauchy-Schwarz inequality,

$$
\begin{aligned}
\left\|L_{n}\right\|_{C \rightarrow C} & =\sum_{j=1}^{m} w_{j}\left|g_{j}\left(x_{0}\right)\right|=\sum_{j=1}^{m} w_{j}\left|G_{n}\left(x_{0}, t_{j}\right)\right| \\
& =\sum_{j=1}^{m} w_{j}^{1 / 2} w_{j}^{1 / 2}\left|G_{n}\left(x_{0}, t_{j}\right)\right| \\
& \leqslant\left(\sum_{j=1}^{m} w_{j}\right)^{1 / 2}\left(\sum_{j=1}^{m} w_{j} G_{n}\left(x_{0}, t_{j}\right)^{2}\right)^{1 / 2} \\
& =\left|S^{r-1}\right|^{1 / 2}\left(\int_{S^{r-1}} G_{n}\left(x_{0}, x\right)^{2} d x\right)^{1 / 2},
\end{aligned}
$$

where in the last step we twice used the property (3.6) of the quadrature rule $Q$. The reproducing kernel property in Lemma 4.1, combined with the expression (4.8) for the "polar" value of $\widetilde{G}_{n}$, gives

$$
\int_{S^{r-1}} G_{n}\left(x_{0}, x\right)^{2} d x=G_{n}\left(x_{0}, x_{0}\right)=\frac{d_{n}}{\left|S^{r-1}\right|},
$$

from which it follows that

$$
\left\|L_{n}\right\|_{C \rightarrow C} \leqslant d_{n}^{1 / 2} .
$$

Now we set $r=3$. To obtain the promised more precise results we need to assume that the family of $m$-point quadrature rules $Q_{m}$ has, in addition to the property (3.6), also a certain regularity property: roughly speaking, that the contribution to the quadrature sum from a spherical cap of a reasonable size, when $Q_{m}$ is applied to the function $f \equiv 1$, is never unboundedly large in relation to the corresponding integral. A "spherical cap of spherical radius $\alpha$ " is the closed cap cut from $S^{2}$ by a cone of half-angle $\alpha$; the "axis" of the spherical cap is the polar axis of the cone. The surface area of a spherical cap of spherical radius $\alpha$ is $2 \pi(1-\cos \alpha) \approx \pi \alpha^{2}$ when $\alpha$ is small. From this it follows that the expected contribution from a spherical cap of spherical radius $1 / \sqrt{m}$ is approximately $\pi(1 / \sqrt{m})^{2}=\pi / m$. In this
light it is natural to require that the contribution from the quadrature points actually found in such a spherical cap be bounded by $c / m$, where $c$ is a constant. This motivates the following assumption, which we shall call the "quadrature regularity" assumption.

Assumption 1 (Quadrature regularity). Let $r=3$. The infinite family of positive-weight $m$-point quadrature rules $\left\{Q_{m}\right\}$ is said to satisfy the quadrature regularity assumption if there exists $c_{1}>0$, with $c_{1}$ independent of $m$, such that for every spherical cap $A$ of spherical radius $1 / \sqrt{m}$ we have

$$
\begin{equation*}
\sum_{t_{j} \in A} w_{j} \leqslant c_{1}|A|, \tag{5.6}
\end{equation*}
$$

where $|A|=2 \pi(1-\cos (1 / \sqrt{m})) \approx \pi / m$ is the surface area of $A$.
In Section 6 we show that many practical quadrature schemes do satisfy this assumption. It follows from the assumption, as we shall see in Lemma 5.5.3, that spherical caps with spherical radius larger than $1 / \sqrt{m}$ display the same regularity property.

We shall also need an analogous regularity result for "spherical collars", where by a spherical collar we mean the difference between two spherical caps with the same axis. The "spherical radii" of a spherical collar which is the difference of spherical caps with spherical radii $\beta$ and $\alpha$, with $\beta>\alpha$, are $\alpha$ and $\beta$. The "height" of such a spherical collar is $\cos \alpha-\cos \beta$, and the "spherical height" is $\beta-\alpha$.

Lemma 5.5.3. Let $\left\{Q_{m}\right\}$ be an infinite family of positive-weight m-point quadrature rules on $S^{2}$ satisfying the quadrature regularity assumption. Then there exist constants $c_{2}, c_{3}>0$, independent of $m$, such that for every spherical cap $A_{\alpha}$ of spherical radius $\alpha \geqslant 1 / \sqrt{m}$ we have

$$
\sum_{t_{j} \in A_{\alpha}} w_{j} \leqslant c_{2}\left|A_{\alpha}\right|,
$$

and for every spherical collar $B_{\alpha, \beta}$ with spherical radii $\alpha, \beta$ with $0<\alpha<\beta \leqslant \pi$ and $\beta-\alpha \geqslant 1 / \sqrt{m}$ we have

$$
\sum_{t_{j} \in B_{\alpha, \beta}} w_{j} \leqslant c_{3}\left|B_{\alpha, \beta}\right| .
$$

Proof. Let $x_{0} \in S^{2}$ be the axis of $A_{\alpha}$ and $B_{\alpha, \beta}$. We first prove the second result for the special case of a spherical collar $B_{\alpha, \beta}$ whose spherical height $\beta-\alpha$ is exactly equal to $1 / \sqrt{m}$.

Let $\gamma=(\beta+\alpha) / 2$, and consider the latitude $\ell_{\gamma}=\left\{x \in S^{2}: x \cdot x_{0}=\cos \gamma\right\}$, which is a circle on $S^{2}$ of radius $\sin \gamma$. We claim that (as pointed out to us by D. Mauersberger, private communication) $B_{\alpha, \beta}$ can be covered by $K=\lceil 2 \pi \sqrt{m} \sin \gamma\rceil$ spherical caps $D_{1}, \ldots, D_{K}$ of spherical radius $1 / \sqrt{m}$, with axes $x_{1}, \ldots, x_{K}$ equally spaced on the circle $\ell_{\gamma}$. To see this, note first that the distance between successive axes (measured along $\ell_{\gamma}$ ) is $2 \pi \sin \gamma / K \leqslant 1 / \sqrt{m}$. Given $x \in B_{\alpha, \beta}$, let $\tilde{x}$ denote the nearest point to $x$ on $\ell_{\gamma}$, and let $x_{j}$ be a spherical cap axis closest to $\tilde{x}$. The great-circle distance between $x$ and $x_{j}$ is bounded above by the sum of the distance between $x_{j}$ and $\tilde{x}$ along $\ell_{\gamma}$ and the great-circle distance between $\tilde{x}$ and $x$, and so is bounded above by $\frac{1}{2}(1 / \sqrt{m})+\frac{1}{2}(1 / \sqrt{m})=1 / \sqrt{m}$, thus $x \in D_{j}$. Thus the claim is established. It follows from this and the quadrature regularity assumption that

$$
\sum_{t_{j} \in B_{\alpha_{\alpha}, \beta}} w_{j} \leqslant K c_{1}\left|D_{1}\right| \leqslant \frac{c_{1} \pi K}{m} \leqslant \frac{c_{1} \pi}{m}(2 \pi \sqrt{m} \sin \gamma+1),
$$

where we have used $\left|D_{1}\right|=2 \pi(1-\cos (1 / \sqrt{m})) \leqslant \pi / m$. We also have

$$
\begin{align*}
\left|B_{\alpha, \beta}\right| & =2 \pi(\cos \alpha-\cos \beta) \\
& =4 \pi \sin \gamma \sin (1 / 2 \sqrt{m}) \\
& \geqslant 4 \sin \gamma / \sqrt{m}, \tag{5.7}
\end{align*}
$$

where in the last step we used $\sin \theta \geqslant 2 \theta / \pi$ for $0 \leqslant \theta \leqslant \pi / 2$. Putting the results together, we have

$$
\sum_{t_{j} \in B_{\alpha, \beta}} w_{j} \leqslant c_{1} \pi\left(\frac{\pi}{2}\left|B_{\alpha, \beta}\right|+\frac{1}{m}\right) \leqslant c_{1} \frac{3 \pi^{2}}{4}\left|B_{\alpha, \beta}\right|,
$$

where in the last step we used (5.7) together with $\sin \gamma \geqslant$ $\sin (1 / 2 \sqrt{m}) \geqslant 1 / \pi \sqrt{m}$ to obtain $1 / m=(\pi / \sqrt{m})(1 /(\pi \sqrt{m})) \leqslant(\pi / 4)\left|B_{\alpha, \beta}\right|$. Thus the spherical collar result is proved for $\beta-\alpha=1 / \sqrt{m}$ with $c_{3}=c_{1} 3 \pi^{2} / 4$.

Now consider an arbitrary spherical collar $B_{\alpha, \beta}$ with $\beta-\alpha \geqslant 1 / \sqrt{m}$. If $\beta-\alpha$ is an integer multiple of $1 / \sqrt{m}$ the result extends trivially, with the same constant as above. Otherwise, following an argument due to D. Mauersberger (private communication), we consider the two sub-collars

$$
B_{\alpha}=B_{\alpha, \alpha+k / \sqrt{m}}, \quad B_{\beta}=B_{\beta-k / \sqrt{m}, \beta},
$$

where $k=\lfloor(\beta-\alpha) \sqrt{m}\rfloor$. Note that $B_{\alpha} \subseteq B_{\alpha, \beta}$ and $B_{\beta} \subseteq B_{\alpha, \beta}$, and that every point of $B_{\alpha, \beta}$ is in at least one of $B_{\alpha}, B_{\beta}$ because $k \geqslant 1$. Thus

$$
\begin{aligned}
\sum_{x_{j} \in B_{\alpha, \beta}} w_{j} & \leqslant \sum_{x_{j} \in B_{\alpha}} w_{j}+\sum_{x_{j} \in B_{\beta}} w_{j} \leqslant c_{1} \frac{3 \pi^{2}}{4}\left(\left|B_{\alpha}\right|+\left|B_{\beta}\right|\right) \\
& \leqslant \frac{c_{1} 3 \pi^{2}}{2}\left|B_{\alpha, \beta}\right| .
\end{aligned}
$$

Thus the spherical collar result is now proved, with $c_{3}=c_{1} 3 \pi^{2} / 2$.
Finally, to prove the spherical cap result for a spherical cap $A_{\alpha}$ of spherical radius $\alpha \geqslant 1 / \sqrt{m}$, let $A$ denote the spherical cap with the same axis and spherical radius $1 / \sqrt{m}$, and let $B_{\alpha}$ be the spherical collar with the same axis and spherical radii $\alpha-k / \sqrt{m}$ and $\alpha$, where $k=\lceil\alpha \sqrt{m}\rceil-1$. Both $A$ and $B_{\alpha}$ are subsets of $A_{\alpha}$, and every point of $A_{\alpha}$ is in at least one of $A$ and $B_{\alpha}$, thus we obtain

$$
\begin{aligned}
\sum_{x_{j} \in A_{\alpha}} w_{j} & \leqslant \sum_{x_{j} \in A} w_{j}+\sum_{x_{j} \in B_{\alpha}} w_{j} \\
& \leqslant c_{1}|A|+c_{1} \frac{3 \pi^{2}}{4}\left|B_{\alpha}\right| \\
& \leqslant c_{1}\left(1+\frac{3 \pi^{2}}{4}\right)\left|A_{\alpha}\right| .
\end{aligned}
$$

Thus the spherical collar result is proved, with $c_{2}=c_{1}\left(1+3 \pi^{2} / 4\right)$.
We now turn to the foreshadowed estimation of $\left\|L_{n}\right\|_{C \rightarrow C}$.
Remark 1. In the following theorem we do not need the property (3.6) of $Q_{m}$. While the theorem can be applied to families of rules $\left\{Q_{m}\right\}$ not satisfying this condition, it needs to be remembered that the estimate (5.1) for the error in $L_{n} f$ is no longer valid in this case.

Remark 2. The condition $m \geqslant(n+1)^{2}$ in the theorem below, relating $m$ (the number of quadrature points) with $n$ (the degree of the spherical polynomial space $\mathbb{P}_{n}^{(r)}$ ) is natural, in that it is shown in [17] to be necessary if (3.6) holds.

Theorem 5.5.4. Let $r=3$. For each $n \geqslant 0$ let $m=m_{n}$ satisfy $m \geqslant(n+1)^{2}$. Moreover let $\left\{Q_{m}\right\}$ be a family of positive-weight m-point quadrature rules satisfying the quadrature regularity assumption. Then there exists $c_{4}>0$, with $c_{4}$ independent of $n$, such that

$$
\begin{equation*}
\left\|L_{n}\right\|_{C \rightarrow C} \leqslant c_{4} n^{1 / 2} \tag{5.8}
\end{equation*}
$$

where $L_{n} f \in \mathbb{P}_{n}^{(3)}$ is the hyperinterpolation approximation associated with $Q_{m}$.

Proof. Let $x_{0}$ satisfy (5.5), so that from Lemma 5.5.1, together with (4.14) and (4.7), we have, on setting $z_{j}=x_{0} \cdot t_{j}$,

$$
\begin{aligned}
\left\|L_{n}\right\|_{C \rightarrow C}=\sum_{j=1}^{m} w_{j}\left|g_{j}\left(x_{0}\right)\right| & =\frac{n+1}{4 \pi} \sum_{j=1}^{m} w_{j}\left|P_{n}^{(1,0)}\left(z_{j}\right)\right| \\
& \leqslant \frac{n+1}{4 \pi} \sum_{z_{j} \geqslant 0} w_{j}\left(\left|P_{n}^{(1,0)}\left(z_{j}\right)\right|+\left|P_{n}^{(0,1)}\left(z_{j}\right)\right|\right),
\end{aligned}
$$

where in the last step we have used $P_{n}^{(1,0)}(-z)=(-1)^{n} P_{n}^{(0,1)}(z)$ (see Szegö [20, Equation (4.1.3)]). Both $\left|P_{n}^{(1,0)}(z)\right|$ and $\left|P_{n}^{(0,1)}(z)\right|$ are bounded by $P_{n}^{(1,0)}(1)=n+1$, from [20, Equation (4.1.1) and the last sentence of page 168]. Together with Equation (7.32.6) of [20] this gives

$$
\begin{equation*}
\left|P_{n}^{(1,0)}(\cos \theta)\right|+\left|P_{n}^{(0,1)}(\cos \theta)\right| \leqslant \min \left(2(n+1), c_{5} n^{-1 / 2} \theta^{-3 / 2}\right), \quad 0 \leqslant \theta \leqslant \frac{\pi}{2} \tag{5.9}
\end{equation*}
$$

for some constant $c_{5}>0$.
We denote the right-hand side of this inequality by $u_{n}(\cos \theta)$. Thus

$$
\begin{equation*}
\left\|L_{n}\right\|_{C \rightarrow C} \leqslant \frac{n+1}{4 \pi} \sum_{z_{j} \geqslant 0} w_{j} u_{n}\left(z_{j}\right), \tag{5.10}
\end{equation*}
$$

where $u_{n}$ is monotone nondecreasing on [0,1]. We split the right-hand side into a "main" term $M$, which contains the contributions to the sum for $0 \leqslant z_{j}<z_{0}$, and a remainder $R$, containing the contributions from the spherical cap $z \geqslant z_{0}$, with $z_{0}$ a number yet to be specified, but which satisfies $0<z_{0} \leqslant 1-1 / n$.

The main term $M$ is to be handled by bounding it above by a Riemann sum, and thence by a 1 -dimensional integral. Thus we partition the interval [ $0, z_{0}$ ] by defining

$$
\xi_{k}=z_{0}-\frac{N-k}{n} \quad \text { for } \quad k=1, \ldots, N,
$$

where $N=\left\lceil n z_{0}\right\rceil \leqslant n-1$, so that

$$
\xi_{1}>0, \xi_{N}=z_{0}, \quad \text { and } \quad \xi_{k+1}-\xi_{k}=\frac{1}{n} \quad \text { for } k=1, \ldots, N-1 .
$$

We also define $\xi_{0}=\xi_{1}-1 / n$ and $\xi_{N+1}=z_{0}+1 / n \leqslant 1$. Now we can write

$$
M=\frac{n+1}{4 \pi} \sum_{0 \leqslant z_{j}<z_{0}} w_{j} u_{n}\left(z_{j}\right)=\frac{n+1}{4 \pi} \sum_{k=0}^{N-1} \sum_{\xi_{k} \leqslant z_{j}<\xi_{k+1}} w_{j} u_{n}\left(z_{j}\right),
$$

where for $z<0$ we define $u_{n}(z)=0$. Using the monotonicity of $u_{n}$, we then deduce

$$
\begin{equation*}
M \leqslant \frac{n+1}{4 \pi} \sum_{k=0}^{N-1}\left(\sum_{\xi_{k} \leqslant z_{j}<\xi_{k+1}} w_{j}\right) u_{n}\left(\xi_{k+1}\right) . \tag{5.11}
\end{equation*}
$$

We may bound the sum of the weights over each spherical collar of height $1 / n$ by appeal to Lemma 5.5.3. (Note that $1 / n>1 / \sqrt{m}$, and that for $0 \leqslant \alpha<\beta \leqslant \pi$ it is clear that the spherical height $\beta-\alpha$ of the spherical collar is greater than the height $\cos \alpha-\cos \beta=1 / n$, from which it follows that $\beta-\alpha \geqslant 1 / n>1 / \sqrt{m}$.) Since the surface area of a spherical collar of height $1 / n$ is $2 \pi / n$, Lemma 5.5 .3 gives

$$
\begin{equation*}
\sum_{\xi_{k} \leqslant z_{j}<\xi_{k+1}} w_{j} \leqslant 2 \pi c_{3} / n . \tag{5.12}
\end{equation*}
$$

Moreover, using again the monotonicity of $u_{n}$ we obtain

$$
\begin{aligned}
\frac{1}{n} \sum_{k=0}^{N-1} u_{n}\left(\xi_{k+1}\right) & \leqslant \sum_{k=0}^{N-1} \int_{\xi_{k+1}}^{\xi_{k+2}} u_{n}(\xi) d \xi=\int_{\xi_{1}}^{\xi_{N+1}} u_{n}(\xi) d \xi \\
& \leqslant \int_{0}^{1} u_{n}(\xi) d \xi \leqslant c_{5} n^{-1 / 2} \int_{0}^{\pi / 2} \theta^{-3 / 2} \sin \theta d \theta \\
& \leqslant c_{5} n^{-1 / 2} \int_{0}^{\pi / 2} \theta^{-1 / 2} d \theta=\sqrt{2 \pi} c_{5} n^{-1 / 2}
\end{aligned}
$$

From this, together with (5.11) and (5.12), it follows that $M \leqslant$ $\sqrt{2 \pi} c_{3} c_{5} n^{1 / 2}$. Note that the sum is independent of $z_{0}$.

Now we turn to the term $R$, given by

$$
R=\frac{n+1}{4 \pi} \sum_{z_{j} \geqslant z_{0}} w_{j} u_{n}\left(z_{j}\right) .
$$

After preliminary study it turns out to be adequate to partition the region $z_{j} \geqslant z_{0}$ into a spherical cap and two spherical collars of appropriate sizes and all with axis $x_{0}$, and to estimate the contribution to $R$ from each using Lemma 5.5.3. Specifically, let $A_{\kappa}$ be the spherical cap with axis $x_{0}$ and with spherical radius $n^{-\kappa}$, where $0<\kappa<1$, let $B_{\gamma}$ be the spherical collar that adjoins $A_{\kappa}$ and has spherical height $n^{-\gamma}$, where $0<\gamma \leqslant \kappa$, and finally let $D$
be the spherical collar that adjoins $B_{\gamma}$ and has height $n^{-1}$. The union $A_{\kappa} \cup B_{\gamma} \cup D$ is the intersection of $S^{2}$ with the half-space $z=\cos \theta \geqslant z_{0}$ if we choose

$$
z_{0}=\cos \left(\frac{1}{n^{\kappa}}+\frac{1}{n^{\nu}}\right)-\frac{1}{n},
$$

which we note ensures $z_{0} \in(0,1-1 / n)$ if $n$ is sufficiently large. Introducing an obvious notation, we may write

$$
\begin{equation*}
R=R\left(A_{\kappa}\right)+R\left(B_{\gamma}\right)+R(D) . \tag{5.13}
\end{equation*}
$$

For the term $R\left(A_{\kappa}\right)$ the first part of Lemma 5.5 .3 is applicable, because $n^{-\kappa}>n^{-1}$ (since $\kappa<1$ ), which in turn exceeds $m^{-1 / 2}$, thus from the lemma and (5.9) we obtain

$$
\begin{aligned}
R\left(A_{\kappa}\right) & \leqslant \frac{n+1}{4 \pi} c_{2}\left|A_{\kappa}\right| u_{n}(1) \leqslant \frac{n+1}{4 \pi} c_{2} \pi\left(n^{-\kappa}\right)^{2} 2(n+1) \\
& =\frac{1}{2} c_{2}(n+1)^{2} n^{-2 \kappa} \leqslant 2 c_{2} n^{2-2 \kappa} .
\end{aligned}
$$

For the term $R\left(B_{\gamma}\right)$ we may again use Lemma 5.5.3, since the spherical height of the collar is $n^{-\gamma}>n^{-1}>m^{-1 / 2}$, thus

$$
\begin{aligned}
R\left(B_{\gamma}\right) & \leqslant \frac{n+1}{4 \pi} c_{3}\left|B_{\gamma}\right| u_{n}\left(\cos n^{-\kappa}\right) \\
& \leqslant \frac{n+1}{4 \pi} c_{3} \pi\left(n^{-\gamma}+n^{-\kappa}\right)^{2} c_{5} n^{-1 / 2}\left(n^{\kappa}\right)^{3 / 2} \leqslant 2 c_{3} c_{5} n^{1 / 2-2 \gamma+3 \kappa / 2},
\end{aligned}
$$

where we used (5.9) and $n^{-\kappa} \leqslant n^{-\gamma}$ (since $0<\gamma \leqslant \kappa$ ).
Finally, for the term $R(D)$ we have, similarly, since $|D|=2 \pi / n$,

$$
\begin{aligned}
R(D) & \leqslant \frac{n+1}{4 \pi} c_{3} \frac{2 \pi}{n} u_{n}\left(\cos \left(n^{-\kappa}+n^{-\gamma}\right)\right) \\
& \leqslant c_{3} u_{n}\left(\cos \left(n^{-\gamma}\right)\right) \leqslant c_{3} c_{5} n^{-1 / 2} n^{3 \gamma / 2} .
\end{aligned}
$$

From these three estimates and (5.13) it follows that $R \leqslant$ $\left(2 c_{2}+3 c_{3} c_{5}\right) n^{1 / 2}$, provided we can simultaneously satisfy

$$
0<\gamma \leqslant \kappa<1,2-2 \kappa \leqslant \frac{1}{2}, \frac{1}{2}-2 \gamma+\frac{3}{2} \kappa \leqslant \frac{1}{2},-\frac{1}{2}+\frac{3}{2} \gamma \leqslant \frac{1}{2} .
$$

Since these are all satisfied by, for example,

$$
\kappa=\frac{3}{4}, \quad \gamma=\frac{2}{3},
$$

it follows from this result and $M \leqslant \sqrt{2 \pi} c_{3} c_{5} n^{1 / 2}<3 c_{3} c_{5} n^{1 / 2}$ that

$$
\left\|L_{n}\right\|_{C \rightarrow C}=M+R \leqslant\left(2 c_{2}+6 c_{3} c_{5}\right) n^{1 / 2}
$$

completing the proof.

## 6. CONFORMING QUADRATURE SCHEMES FOR $r=3$

In this section we show that many quadrature schemes possess the quadrature regularity property. We begin with a simple sufficient condition.

Proposition 6.6.1. An infinite family of m-point quadrature rules $\left\{Q_{m}\right\}$ with positive weights $w_{1}, \ldots, w_{m}$ and points $x_{1}, \ldots, x_{m} \in S^{2}$ satisfies the quadrature regularity property if there exist $a_{1}, a_{2}>0$, independent of $m$, such that

$$
\begin{equation*}
w_{j} \leqslant \frac{a_{1}}{m}, \quad j=1, \ldots, m \tag{6.1}
\end{equation*}
$$

and

$$
\begin{equation*}
\Varangle\left(x_{j}, x_{k}\right) \geqslant \frac{a_{2}}{\sqrt{m}}, \quad j, k=1, \ldots, m, \quad j \neq k . \tag{6.2}
\end{equation*}
$$

Proof. For an arbitrary spherical cap $A_{m}$ of spherical radius $1 / \sqrt{m}$, it follows readily from (6.2) that the number of points contained in $A_{m}$ is bounded independently of $m$. The quadrature regularity property then follows immediately from (6.1) on noting that $\left|A_{m}\right|$ is of exact order $1 / m$.

One important class of quadrature rules does not in general satisfy the conditions of Proposition 6.6.1, but nevertheless can be quadrature regular. These are the tensor-product rules, which we may introduce this way. The surface integral of $f \in C\left(S^{2}\right)$ can be written as

$$
\begin{align*}
\int_{S^{r-1}} f(x) d x & =\int_{0}^{2 \pi} \int_{0}^{\pi} f(\theta, \phi) \sin \theta d \theta d \phi \\
& =\int_{0}^{2 \pi} \int_{-1}^{1} F(z, \phi) d z d \phi, \tag{6.3}
\end{align*}
$$

where $\phi$ is the azimuthal angle and $\theta$ the polar angle, $z=\cos \theta$, and $F(\cos \theta, \phi)=f(\theta, \phi)$. A tensor-product rule for the integral (6.3) is a rule of the form

$$
\begin{equation*}
\sum_{k} \mu_{k} \sum_{j} v_{j} F\left(z_{j}, \phi_{k}\right)=q_{\phi} q_{z} F, \tag{6.4}
\end{equation*}
$$

where

$$
\begin{equation*}
q_{\phi} g:=\sum_{k} \mu_{k} g\left(\phi_{k}\right), \quad q_{z} h:=\sum_{j} v_{j} h\left(z_{j}\right) \tag{6.5}
\end{equation*}
$$

for appropriate choices of the 1-dimensional rules $q_{\phi}$ and $q_{z}$, and with both sums finite. For the azimuthal integration a sensible choice for the rule $q_{\phi}$, and the only one considered here, is the rectangle rule with spacing $\pi /(n+1)$,

$$
\begin{equation*}
q_{\phi} g:=\frac{\pi}{n+1} \sum_{k=0}^{2 n+1} g\left(\frac{k \pi}{n+1}\right) \tag{6.6}
\end{equation*}
$$

because this rule is exact for all trigonometric polynomials of degree $\leqslant 2 n+1$.

To see how the rule $q_{z}$ should be chosen, recall that the tensor-product rule $q_{\phi} q_{z}$ is required to be exact for all spherical polynomials of degree $\leqslant 2 n$. Equivalently, we need the rule $q_{\phi} q_{z}$ to be exact if $f$ is an arbitrary spherical harmonic $Y_{\ell, k}$ of degree $\leqslant 2 n$. The spherical harmonics can be chosen as

$$
Y_{\ell, k}(\theta, \phi)= \begin{cases}c_{\ell m} P_{\ell}^{m}(\cos \theta) \cos m \phi & \text { for } \quad k=2 m+1, m=0, \ldots, \ell \\ c_{\ell m} P_{\ell}^{m}(\cos \theta) \sin m \phi & \text { for } \quad k=2 m, m=1, \ldots, \ell,\end{cases}
$$

where $P_{\ell}^{m}$ is an associated Legendre function of the first kind. Our choice of azimuthal quadrature rule already ensures, because $m \leqslant \ell$, that $\cos m \phi$ and $\sin m \phi$ are integrated exactly for all $\ell \leqslant 2 n$, and therefore ensures that

$$
q_{\phi} Y_{\ell, k}=0 \quad \text { for } \quad 2 \leqslant k \leqslant 2 \ell+1,0 \leqslant \ell \leqslant 2 n
$$

Thus the desired property holds for spherical harmonics $Y_{\ell, k}$ with $k>1$, and it only remains to prove it for $k=1$. Since $P_{\ell}^{0}=P_{\ell}$, the Legendre polynomial, it follows that the property will hold if and only if

$$
\begin{equation*}
q_{z} h=\int_{-1}^{1} h(z) d z \quad \forall h \in \mathbb{P}_{2 n}[-1,1] . \tag{6.7}
\end{equation*}
$$

In words, the requirement is that the rule $q_{z}$ be of algebraic degree of precision at least $2 n$.

Example 6.1. Here we choose $q_{z}$, the quadrature rule over $z$, to be the $(n+1)$-point Gauss-Legendre rule. Then (6.7) is satisfied, because this rule has degree of precision $2 n+1$. This choice gives $m=2(n+1)^{2}$ for the total number of points. (Stroud [19] gives analogous tensor product Gauss
rules of specified precision for the sphere for all $r \geqslant 3$.) The hyperinterpolation approximation obtained with this rule has been studied in [10], and the non-optimal result $\left\|L_{n}\right\|_{C \rightarrow C} \leqslant c n^{2}$ is proved there.

Example 6.2. Next choose $q_{z}$ to be the Clenshaw-Curtis rule [4],

$$
q_{z} h=\sum_{j=0}^{2 n} v_{j} h\left(\cos \frac{j \pi}{2 n}\right) .
$$

This is an interpolatory rule, in which (as pointed out by Imhof [12]), the weights can be written explicitly as

$$
\begin{align*}
& v_{0}=v_{2 n}=\frac{1}{n} \sum_{k=0}^{n} \frac{1}{1-4 k^{2}}  \tag{6.8a}\\
& v_{j}=v_{2 n-j}=\frac{2}{n} \sum_{k=0}^{n \prime \prime} \frac{1}{1-4 k^{2}} \cos \frac{k j \pi}{n}, \quad j=1, \ldots, n . \tag{6.8b}
\end{align*}
$$

(The double prime on the sum indicates that the first and last terms are to be halved.)

This is a positive-weight rule (see [12]) with degree of precision $2 n+1$. The resulting value of $m$ is

$$
m=(2 n-1) 2(n+1)+2=4 n\left(n+\frac{1}{2}\right)=4 n^{2}+2 n,
$$

where we have taken account of the fact that on the sphere there is only one point with $z=+1$, and one with $z=-1$.

Example 6.3. In 1933 Fejér [8] discussed an interpolatory quadrature formula based on the "Filippi" points, which are the Clenshaw-Curtis quadrature points excluding the two end-points. The rule was rediscovered recently by [7, Section 4]. The Fejér rule of the appropriate precision is

$$
\begin{equation*}
q_{z} h=\sum_{j=1}^{2 n+1} v_{j} h\left(\cos \frac{j \pi}{2 n+2}\right), \tag{6.9}
\end{equation*}
$$

where

$$
v_{j}=\frac{2}{n+1} \sin \left(\frac{j \pi}{2 n+2}\right) \sum_{\ell=1}^{n+1} \frac{1}{2 \ell-1} \sin \left(\frac{(2 \ell-1) j \pi}{2 n+2}\right), \quad j=1, \ldots, 2 n+1 .
$$

It was shown by [8] that $v_{j}>0$ for $j=1, \ldots, 2 n+1$. The hyperinterpolation approximation with this choice of quadrature rule was in effect discussed by [13], and $\left\|L_{n}\right\|_{C \rightarrow C}$ shown there to be of order $O\left(n^{1 / 2}\right)$. With this rule the value of $m$ is

$$
m=(2 n+1)(2 n+2)=4 n^{2}+6 n+2 .
$$

Each of the quadrature rules in the three examples above has precision at least $2 n$, and therefore generates a valid hyperinterpolation approximation, when combined with the rectangle rule (6.6). It remains to show that these tensor-product rules satisfy the quadrature regularity assumption. The following theorem states a sufficient condition for this property to hold, which is general enough to include all three examples.

Theorem 6.6.2. For given $n \geqslant 0$, let $q_{\phi} q_{z}$ be a tensor-product rule, with $q_{\phi}$ given by (6.6) and $q_{z}$ by the positive weight rule

$$
q_{z} h=\sum_{j=1}^{J} v_{j} h\left(z_{j}\right),
$$

with $1 \geqslant z_{1}>z_{2}>\cdots>z_{J} \geqslant-1$, and $J \geqslant 4$. With $\cos \theta_{j}:=z_{j}, 0 \leqslant \theta_{j} \leqslant \pi$, the quadrature regularity assumption holds for these rules if the following properties all hold for some positive constants $a_{0}, a_{1}, a_{2}, a_{3}, a_{4}$ :

$$
\begin{align*}
a_{0}(n+1) & \geqslant J \geqslant a_{1}(n+1),  \tag{6.10a}\\
0 & <v_{j} \leqslant a_{2} \frac{\sin \theta_{j}}{n+1}+\frac{a_{3}}{(n+1)^{2}}, \quad j=1, \ldots, J,  \tag{6.10b}\\
\theta_{j+1}-\theta_{j} & \geqslant \frac{a_{4}}{n+1}, \quad j=1, \ldots, J-1 . \tag{6.10c}
\end{align*}
$$

Proof. Note first that $2(n+1)(J-2)+2 \leqslant m \leqslant 2(n+1) J$, and that in consequence $a_{1}(n+1)^{2} \leqslant m \leqslant 2 a_{0}(n+1)^{2}$ for $J \geqslant 4$.

Let $A$ be a spherical cap of spherical radius $1 / \sqrt{m}$ and axis ( $\theta_{0}, \phi_{0}$ ). Our aim is to prove (5.6) for some constant $c$. It follows from assumptions (6.10c) and (6.10a) that only a bounded number of $j$-values can contribute to the sum of the weights in (5.6): the number of contributing $j$-values is bounded above by $\left\lfloor(2 / \sqrt{m}) /\left(a_{4} /(n+1)\right)\right\rfloor+1 \leqslant\left\lfloor 2 /\left(a_{4} \sqrt{a_{1}}\right)\right\rfloor+1=: a_{5}$ if $J \geqslant 4$. Noting that it is sufficient to establish the quadrature regularity property for each term of the bound in (6.10b) taken separately, we consider first the case $v_{j} \leqslant a_{3} /(n+1)^{2}$. In this case the sum of weights $\mu_{k} v_{j}=$ $\pi v_{j} /(n+1)$ from quadrature points in $A$ is bounded by $2 \pi a_{5} a_{3} /(n+1)^{2} \leqslant$ $4 \pi a_{0} a_{3} a_{5} / m$, so that for this term the quadrature regularity assumption holds.

Now suppose that $v_{j} \leqslant a_{2} \sin \theta_{j} /(n+1)$. Since $\mu_{k}=\pi /(n+1)$ for $k=0, \ldots, 2 n+1$, the spherical cap assumption holds in this case if we can show, for each value of $j$ that contributes to the sum of the weights over the spherical cap, that the number $n_{j}$ of contributing $k$ values (i.e. $\left.n_{j}:=\#\left\{\left(\theta_{j}, \phi_{k}\right) \in A, k=0, \ldots, 2 n+1\right\}\right)$ satisfies

$$
\begin{equation*}
n_{j} \leqslant a_{6} / \sin \theta_{j} \tag{6.11}
\end{equation*}
$$

for some constant $a_{6}>0$. This is because in this case the bound for the sum of the quadrature weights is

$$
\sum_{\left(\theta_{j}, \phi_{k}\right) \in A} \mu_{k} v_{j} \leqslant \sum_{j=1}^{J} n_{j} \frac{\pi}{n+1} v_{j} \leqslant \sum_{j=1}^{J} \frac{a_{6}}{\sin \theta_{j}} \frac{\pi}{n+1} \frac{a_{2} \sin \theta_{j}}{n+1} \leqslant \frac{2 \pi a_{0} a_{2} a_{5} a_{6}}{m}
$$

In order to prove (6.11), observe that the constant distance between the points $\left(\theta_{j}, \phi_{k}\right)$ and $\left(\theta_{j}, \phi_{k+1}\right)$ measured along the latitude $\theta=\theta_{j}$ is $\pi \sin \theta_{j} /(n+1)$, whereas the total length of the intersection of that latitude with $A$ is bounded above by the circumference of $A$, and hence by $2 \pi / \sqrt{m}$. It follows that

$$
n_{j} \leqslant \frac{2 \pi / \sqrt{m}}{\pi \sin \theta_{j} /(n+1)}+1 \leqslant \frac{a_{6}}{\sin \theta_{j}},
$$

with $a_{6}=1+2 / \sqrt{a_{1}}$. This proves (6.11), completing the proof.
We now show that all three of the Examples above satisfy the conditions of the theorem.

Corollary 6.6.3 Each of Examples 1, 2 and 3 satisfies the quadrature regularity assumption.

Proof. We show that the conditions (6.10) of Theorem 6.6.2 are satisfied in each case. We begin with Example 6.3. Note first that the weight $v_{j}$ in the rule (6.9) is bounded by

$$
\begin{equation*}
\left|v_{j}\right| \leqslant \frac{c}{n+1} \sin \left(\frac{j \pi}{2 n+2}\right)=\frac{c}{n+1} \sin \theta_{j}, \quad j=1, \ldots, 2 n+1, \tag{6.12}
\end{equation*}
$$

where $\theta_{j}=j \pi /(2 n+2)$. This follows from the fact that $(4 / \pi)$ $\sum_{\ell \geqslant 1}(2 \ell-1)^{-1} \sin (2 \ell-1) \theta$ is the Fourier series of the $2 \pi$-periodic function whose value is 1 on $(0, \pi)$ and -1 on $(-\pi, 0)$. Although the partial sums exhibit the Gibbs phenomenon, their uniform norms are well known to be uniformly bounded.

Since $J=2 n+2$ and $\theta_{j}=\pi /(2 n+2)$, it is now clear that the conditions of Theorem 6.6.2 are satisfied, with $a_{3}=0, a_{0}=a_{1}=2$ and $a_{4}=\pi / 2$.

Now consider the case of Example 6.2, the Clenshaw-Curtis rule. With $\theta_{j}$ now defined by

$$
\theta_{j}=\frac{j \pi}{2 n}, \quad j=0, \ldots, 2 n,
$$

it follows from (6.8) that the Clenshaw-Curtis weights can be written as

$$
v_{j}=\frac{2}{n} \alpha_{j} \sum_{k=0}^{n} \frac{1}{1-4 k^{2}} \cos 2 k \theta_{j}, \quad j=0, \ldots, 2 n,
$$

with $\alpha_{0}=\alpha_{2 n}=1 / 2$ and $\alpha_{j}=1, j=1, \ldots, 2 n-1$. Now we observe that the Fourier series of the even, $2 \pi$-periodic function $|\sin \theta|$ is

$$
|\sin \theta|=\frac{4}{\pi} \sum_{k=0}^{\infty} \frac{1}{1-4 k^{2}} \cos 2 k \theta,
$$

where the single prime indicates that the first term is to be halved. This allows the weights $v_{j}$ to be written in the form

$$
\begin{equation*}
v_{j}=\frac{\pi}{2 n} \alpha_{j} \sin \theta_{j}-r_{j}, \quad j=0, \ldots, 2 n, \tag{6.13}
\end{equation*}
$$

where

$$
r_{j}=\frac{2}{n} \alpha_{j} \sum_{k=n}^{\infty} \frac{1}{4 k^{2}-1} \cos \theta_{j} .
$$

The second term of (6.13), being an absolutely convergent Fourier series, can be bounded by
$\left|r_{j}\right| \leqslant \frac{1}{2 n} \sum_{k=n}^{\infty} \frac{1}{(k-1)^{2}} \leqslant \frac{1}{2 n} \int_{n-2}^{\infty} \frac{1}{x^{2}} d x=\frac{1}{2 n(n-2)} \leqslant \frac{8}{3(n+1)^{2}} \quad$ if $n \geqslant 3$.
It is clear from this bound and (6.13) that the three conditions of Theorem 6.6 .2 are satisfied. This completes the proof for Example 6.2.

Finally, we turn to Example 6.1 and the Gauss rule. In this case $J=n+1$, and according to Szegö [20, Equation (5.3.14)],

$$
v_{j} \leqslant c \frac{\theta_{j}}{n+1}, \quad j=1, \ldots,\left\lfloor\frac{n+1}{2}\right\rfloor,
$$

from which it follows, using $\theta \leqslant \pi / 2 \sin \theta$ for $0 \leqslant \theta \leqslant \pi / 2$, together with $v_{j}=v_{n+2-j}, \theta_{j}=\pi-\theta_{n+2-j}$ for $j=1, \ldots, n+1$ that

$$
v_{j} \leqslant c \frac{\sin \theta_{j}}{n+1}, \quad j=1, \ldots, n+1
$$

Finally it is known (see [20, Theorem 6.21.2]) that

$$
\frac{2 j-1}{2 n+3} \pi \leqslant \theta_{j} \leqslant \frac{2 j}{2 n+3} \pi, \quad j=1, \ldots, n+1,
$$

from which follows

$$
\theta_{j+1}-\theta_{j} \geqslant \frac{\pi}{2 n+3}, \quad j=1, \ldots, n,
$$

completing the proof.
Before concluding this section, we note one class of tensor-product rule for which the validity of the quadrature-regularity property is open. These are the tensor-product "spherical $t$-designs" of Bajnok [1], which are rules of the form (6.4), (6.5), (6.6), and with the rule $q_{z}$ of the equal weight form

$$
q_{z} h=\frac{2}{J} \sum_{j=1}^{J} h\left(z_{j}\right) .
$$

Bajnok proves the existence of rules of this form that are exact for all $h \in \mathbb{P}_{2 n}$ and for all $J$ sufficiently large: specifically, he shows existence for

$$
J \geqslant 2(2 n)^{2}(2 n+1) \sqrt{(2 n+2)(4 n+1)(4 n+2 \sqrt{4 n+4})+5} .
$$

Note that $J$ is very large, the right hand side being of order $O\left(n^{4.5}\right)$, thus Theorem 6.6.2 is not available. The practical usefulness of rules with such a large number of points must be questionable.

## 7. INTERPOLATION IN THE UNIFORM NORM

For completeness we briefly review known results for the interpolatory approximation $\Lambda_{n} f$ in the uniform norm.

Given a fundamental system $\left\{x_{1}, \ldots, x_{d_{n}}\right\}$, the Lagrange polynomials $\left\{\ell_{1}, \ldots, \ell_{d_{n}}\right\} \subseteq \mathbb{P}_{n}$ are defined, as usual, by

$$
\begin{equation*}
\ell_{j} \in \mathbb{P}_{n}, \quad \ell_{j}\left(x_{i}\right)=\delta_{j i}, \quad i, j=1, \ldots, d_{n} \tag{7.1}
\end{equation*}
$$

For given $f \in C\left(S^{r-1}\right)$ the classical expression for $\Lambda_{n} f$ is then

$$
\begin{equation*}
\Lambda_{n} f=\sum_{j=1}^{d_{n}} f\left(x_{j}\right) \ell_{j}, \tag{7.2}
\end{equation*}
$$

which manifestly satisfies the interpolatory property (3.1). From this it follows easily that

$$
\begin{equation*}
\left\|\Lambda_{n}\right\|_{C \rightarrow C}=\max _{x \in S^{r-1}} \sum_{j=1}^{d_{n}}\left|\ell_{j}(x)\right| \tag{7.3}
\end{equation*}
$$

which is the so-called Lebesgue constant for interpolation.
The value of $\left\|\Lambda_{n}\right\|_{C \rightarrow C}$ depends on the choice of the fundamental system $\left\{x_{1}, \ldots, x_{d_{n}}\right\}$. One knows that $\left\|\Lambda_{n}\right\|_{C \rightarrow C}$ can be made arbitrarily large if the fundamental system is badly chosen. The interesting question is how small $\left\|\Lambda_{n}\right\|_{C \rightarrow C}$ can be made by a judicious choice of fundamental system. Little is known about this question.

One known result, from the work of Reimer [16], is that there exists a fundamental system with $\left\|\Lambda_{n}\right\|_{C \rightarrow C} \leqslant d_{n}$. This property holds if the fundamental system is "extremal". A fundamental system $X=\left\{x_{1}, \ldots, x_{d_{n}}\right\}$ is extremal if it maximizes $\mid \operatorname{det} S\left(x_{1}, \ldots, x_{d_{n}}\right)$, where

$$
S\left(x_{1}, \ldots, x_{d_{n}}\right)=\left[\begin{array}{ccc}
s_{1}\left(x_{1}\right) & \cdots & s_{1}\left(x_{d_{n}}\right) \\
\vdots & \ddots & \vdots \\
s_{d_{n}}\left(x_{1}\right) & \cdots & s_{d_{n}}\left(x_{d_{n}}\right)
\end{array}\right],
$$

and $\left\{s_{1}, \ldots, s_{d_{n}}\right\}$ is any fixed basis for $\mathbb{P}_{n}$. The significance of the fundamental system being extremal follows from the explicit representation for $\ell_{j}$,
$\ell_{j}(x)=\frac{\operatorname{det} S\left(x_{1}, \ldots, x_{j-1}, x, x_{j+1}, \ldots, x_{d_{n}}\right)}{\operatorname{det} S\left(x_{1}, \ldots, x_{j-1}, x_{j}, x_{j+1}, \ldots, x_{d_{n}}\right)}, \quad j=1, \ldots, d_{n}, \quad x \in S^{r-1}$,
in that the extremal property gives immediately

$$
\left\|\ell_{j}\right\|_{\infty}=1, \quad j=1, \ldots, d_{n}
$$

and hence from (7.3)

$$
\left\|\Lambda_{n}\right\|_{C \rightarrow C} \leqslant d_{n}
$$

This bound, which for $r=3$ gives $\left\|\Lambda_{n}\right\|_{C \rightarrow C} \leqslant(n+1)^{2}$, is sometimes very pessimistic.

Reimer [15] and Freeden et al. [9] have pointed out that the "Lagrangian square sums" can play a useful role in the estimation of
$\left\|\Lambda_{n}\right\|_{C \rightarrow C}$, in the following way. By an application of the Cauchy-Schwarz inequality to (7.3), we obtain

$$
\begin{equation*}
\left\|\Lambda_{n}\right\|_{C \rightarrow C} \leqslant d_{n}^{1 / 2} \max _{x \in S^{r-1}}\left(\sum_{j=1}^{d_{n}} \ell_{j}(x)^{2}\right)^{1 / 2} . \tag{7.4}
\end{equation*}
$$

Now the matrix $G$ with elements defined by (4.3) and (4.12) is a symmetric positive-definite matrix, with eigenvalues $\lambda_{j}$ which can be chosen to satisfy

$$
0<\lambda_{\min }=\lambda_{1} \leqslant \cdots \leqslant \lambda_{d_{n}}=\lambda_{\max } .
$$

It is well known that upper and lower bounds on the Lagrangian square sums are given by

$$
\frac{G_{n}(x, x)}{\lambda_{\max }} \leqslant \sum_{j=1}^{d_{n}} \ell_{j}(x)^{2} \leqslant \frac{G_{n}(x, x)}{\lambda_{\min }},
$$

which is Theorem 1 of Reimer [15] or Lemma 7.2.1 of Freeden et al. [9]. Noting that $G_{n}(x, x)$ is independent of $x$, it is useful to rewrite this as

$$
\begin{equation*}
\frac{\lambda_{\text {avg }}}{\lambda_{\text {max }}} \leqslant \sum_{j=1}^{d_{n}} \ell_{j}(x)^{2} \leqslant \frac{\lambda_{\text {avg }}}{\lambda_{\text {min }}}, \tag{7.5}
\end{equation*}
$$

where by (4.8),

$$
\begin{equation*}
\lambda_{\text {avg }}:=\frac{\lambda_{1}+\cdots+\lambda_{d_{n}}}{d_{n}}=\frac{\operatorname{Tr} G}{d_{n}}=\tilde{G}_{n}(1)=\frac{d_{n}}{\left|S^{r-1}\right|}, \tag{7.6}
\end{equation*}
$$

since all diagonal elements have the same value $\widetilde{G}_{n}(1)$. Using (7.5) together with (7.4) now gives

$$
\begin{equation*}
\left\|\Lambda_{n}\right\|_{C \rightarrow C} \leqslant d_{n}^{1 / 2}\left(\frac{\lambda_{\mathrm{avg}}}{\lambda_{\min }}\right)^{1 / 2} \tag{7.7}
\end{equation*}
$$

which is Corollary 2 of [15] and Lemma 7.2.2 of [9].
Reimer notes in particular (in Corollary 3 of [15]) that in the special case that the eigenvalues are all equal, i.e. $\lambda_{1}=\cdots=\lambda_{d_{n}}$, the result reduces to

$$
\begin{equation*}
\left\|\Lambda_{n}\right\|_{C \rightarrow C} \leqslant d_{n}^{1 / 2} . \tag{7.8}
\end{equation*}
$$

This result is also given by Theorem 5.5.2 for the hyperinterpolation operator, if we use the fact (see [18]) that interpolation is a special case of hyperinterpolation when the eigenvalues are all equal. We note, though, that for $r \geqslant 3$ and $n \geqslant 3$ the eigenvalues can not be equal. This follows (as
pointed out by [16]) from the fact that equality of the eigenvalues would imply, via (7.5), that $\sum \ell_{j}(x)^{2} \equiv 1$ for $x \in S^{r-1}$, yet the latter is shown by Bos [3] to be impossible for $r \geqslant 3$ and $n \geqslant 3$.

At the present time it is an open question whether the bound (7.7) can be improved. In the case $r=3$ the bound is $(n+1)\left(\lambda_{\text {avg }} / \lambda_{\min }\right)^{1 / 2} \geqslant n+1$. In a future paper we shall report empirical indications of the existence of fundamental systems that give a rate of growth for the norm $\left\|\Lambda_{n}\right\|$ close to $O(n)$.

## ACKNOWLEDGMENTS

The support of the Australian Research Council is gratefully acknowledged, as is the assistance of Mr. D. Mauersberger, who read the manuscript in draft form and made many useful contributions.

## REFERENCES

1. B. Bajnok, Construction of designs on the 2-sphere, Europ. J. Combinatorics 12 (1991), pp. 377-382.
2. D. L. Berman, On a class of linear operators, Dokl. Akad. Nauk SSSR 85 (1952), pp. 13-16. (Russian), Math. Reviews 14, 57.
3. L. Bos, Some remarks on the Fejér problem for Lagrange interpolation in several variables, J. Approx. Theory 60 (1990), pp. 133-140.
4. C. W. Clenshaw and A. R. Curtis, A method for numerical integration on an automatic computer, Numer. Math. 2 (1960), pp. 197-205.
5. I. K. Daugavet, Some applications of the Marcinkiewicz-Berman identity, Vestnik Leningrad Univ. Math. 1 (1974), pp. 321-327.
6. P. J. Davis, "Interpolation and Approximation," Blaisdell, New York, 1963.
7. J. R. Driscoll and D. M. Healy, Jr., Computing Fourier transforms and convolutions on the 2 -sphere, Adv. in Appl. Math. 15 (1994), pp. 202-250.
8. L. Fejér, Mechanische Quadraturen mit positiven Cotesschen Zahlen, Math. Z. 87 (1933), pp. 287-308.
9. W. Freeden, T. Gervens, and M. Schreiner, "Constructive Approximation on the Sphere," Clarendon Press, Oxford, 1998.
10. M. Ganesh, I. Graham, and J. Sivaloganathan, A pseudospectral three-dimensional boundary integral method applied to a nonlinear model problem from finite elasticity, SIAM J. Numer. Anal. 31 (1994), pp. 1378-1414.
11. T. H. Gronwall, On the degree of convergence of Laplace's series, Trans. Amer. Math. Soc. 15 (1914), pp. 1-30.
12. J. P. Imhof, On the method for numerical integration of Clenshaw and Curtis, Numer. Math. 5 (1963), pp. 138-141.
13. A. K. Kushpel and J. Levesley, "Radial Quasi-Interpolation on $S^{2}$," Tech. rep., Mathematics and Computer Science, University of Leicester, 1998; also Quasi-interpolation on the 2 -sphere using radial polynomials, J. Approx. Theory 102 (2000), 141-154, doi:10.1006/jath.1999.3373.
14. C. Müller, "Spherical Harmonics," Vol. 17, Lecture Notes in Mathematics, Springer Verlag, Berlin/New York, 1966.
15. M. Reimer, Interpolation on the sphere and bounds for the Lagrangian square sums, Results in Mathematics 11 (1987), pp. 144-166.
16. M. Reimer, "Constructive Theory of Multivariate Functions," BI Wissenschaftsverlag, Mannheim/Wien/Zürich, 1990.
17. I. H. Sloan, Polynomial interpolation and hyperinterpolation over general regions, J. Approx. Theory 83 (1995), pp. 238-254.
18. I. H. Sloan, Interpolation and hyperinterpolation on the sphere, in "Multivariate Approximation: Recent Trends and Results" (W. Haussmann, K. Jetter, and M. Reimer, Eds.), pp. 255-268, Akademie Verlag GmbH, Berlin (Wiley-VCH), 1997.
19. A. H. Stroud, "Approximate Calculation of Multiple Integrals," Prentice-Hall, Englewood Cliffs, 1971.
20. G. Szegö, "Orthogonal Polynomials," Vol. 23, American Mathematical Society Colloquium Publications, American Mathematical Society, Providence, RI, 4th ed., 1975.
